

| <b>FEATURES</b>   | <b>MIKADO FIND</b> | <b>MIKADO SELECT</b> | <b>MIKADO CONTROL</b> |
|---|--------------------|----------------------|-----------------------|
| Robot interface with integrated pathplanning                  |                    |                      | ●                     |
| Virtual simulation environment                                |                    |                      | ●                     |
| Scene creation  |                    |                      | ●                     |
| Check of collision  |                    | ●                    | ●                     |
| Sequence programming  |                    | ●                    | ●                     |
| Selection of grasping positions                               |                    | ●                    | ●                     |
| Hand-eye-calibration (parts found in robot coordinate system) | ●                  | ●                    | ●                     |
| Saving product's parameters for automatic product change      | ●                  | ●                    | ●                     |
| Detecting products and communicate their orientation          | ●                  | ●                    | ●                     |
| 3D pointcloud   | ●                  | ●                    | ●                     |
| PLC interface   | ●                  | ●                    | ●                     |

Grasping position

OPC-UA, TCP

OPC-UA, TCP, Profinet, Ethercat